



Stability, Training, and Protection in High Current Density Windings*

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Superconducting Magnet Program



Acknowledgments

The data and a majority of the ideas and concepts are the work of or done with, or derived from discussions with colleagues in the research groups of which I am a member. The groups are: Lawrence Berkeley National Lab AFRD Superconducting Magnet Group S. Bartlett, B. Benjegerdes, P. Bish, D. Byford, S. Caspi, L. Chiesa, K. Chow, M. Coccoli, S. Dardin, D. Dell'Orco, D. Dietderich, P. Ferracin, S. Gourlay, M. Goli, R Gupta, R. Hafalia, R. Hannaford, W. Harnden, H. Higley, A. Jackson, T. Jaffrey, A. Lietzke, N. Liggins, S. Mattafirri, G. Millos, L. Morrison, M. Morrison, M. Nyman, R. Oort, E. Palmerston, J. Remenarich, G. Sabbi, R. Scanlan, J. Smithwick, J. Swanson, C. Taylor, J. van Oort

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The stability estimate development is given in detail in Dr. M. Wilson's Book "Superconducting Magnets" Chapters 5 through 7. Some particular equations and relationships were first given in BNL 51412 "Stability of Superconducting ISABELLE Dipole Magnets by Stefan Wipf April 1981



Windings, cables, strands, and sub-elements

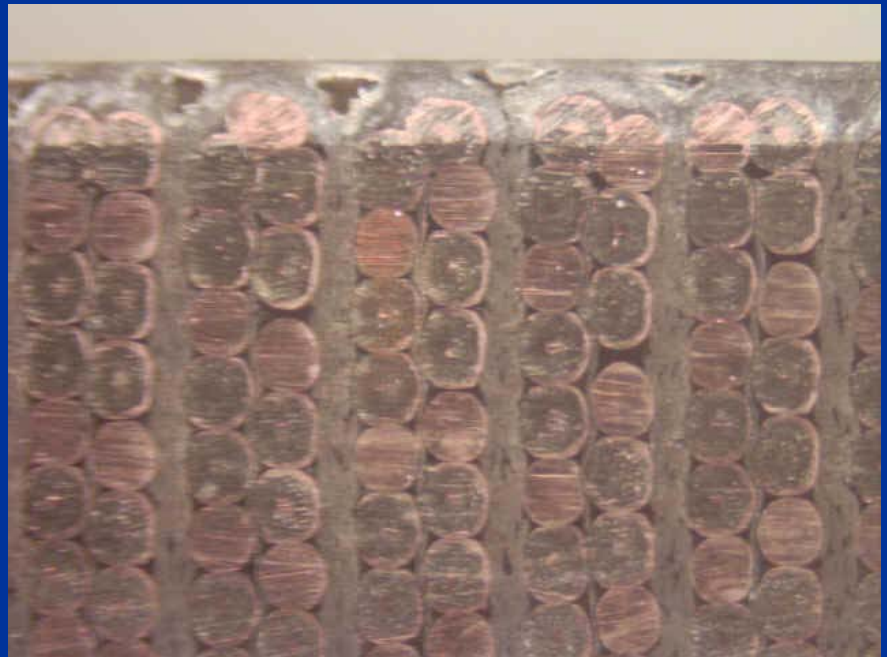
- Maximum Compaction w/o degradation
- No Void Space, no epoxy volumes unfilled with fiber glass
- Winding's Desirable Properties
 - Monolithic winding pack
 - No bonding to support surfaces with a shear force (or release)
 - Pre-exercise to obtain the best modulus (load & unload)





Windings, Cables, strands, and sub-elements

- Boundary Value Currents
- Cross strand Resistance
 - non-cored
 - cored
- Highest Compaction w/o degradation
- Minimize Epoxy space with glass and surfaces with mica or release agent
- Minimize Insulation film minimum thickness

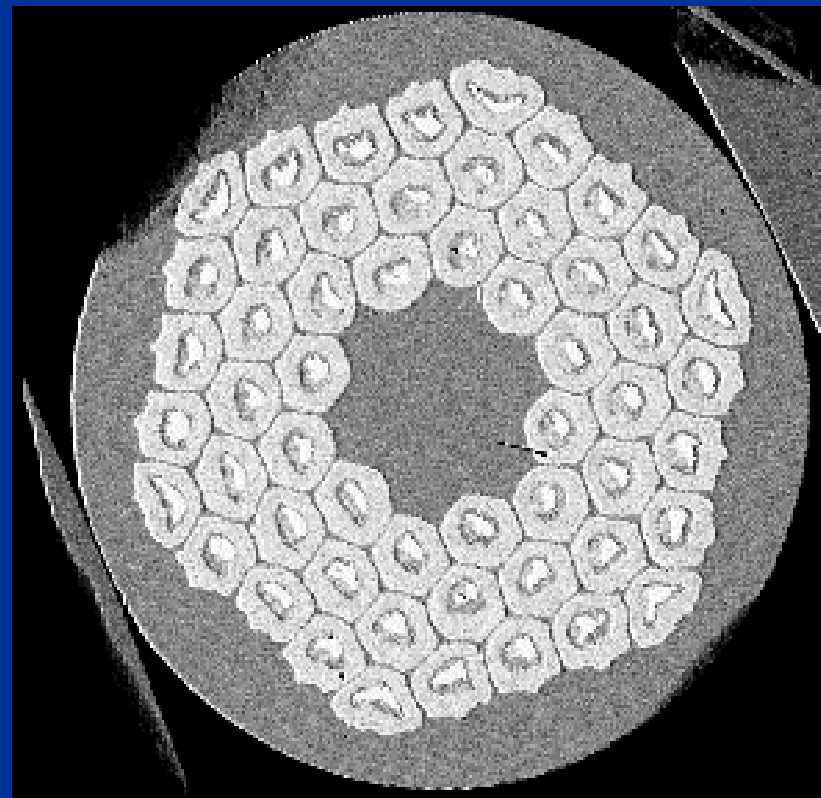




Windings, Cables, Strands, and sub-elements

Strand Stability Estimate Calculations

- > Self Field $B_o = \mu_o I_t / 2\pi a \sim 0.46T$
- > Diffusivity
 - $D_{\Theta} = K/C_v$
 - $D_m = \rho/\mu_o$
- > Time Constants of Composite
 - Surface heat transfer $\sim 5.2 \times 10^{-3}s$
 - Magnetic Flux $\sim 5.1 \times 10^{-3}s$
 - Internal heat transfer $\sim 1.7 \times 10^{-3}s$





Windings, Cables, Strands, and Sub-elements

Composite & Sub-Element Stability Estimate Calculations

“Dynamic Stability Calculations”

$$a < 8^{1/2}d$$

$$d^2 = K(\theta_c - \theta_o)(1 - \lambda)/\lambda J^2 \rho$$

$$d \sim 41 \mu\text{m}$$

$$a = 116 \mu\text{m}$$

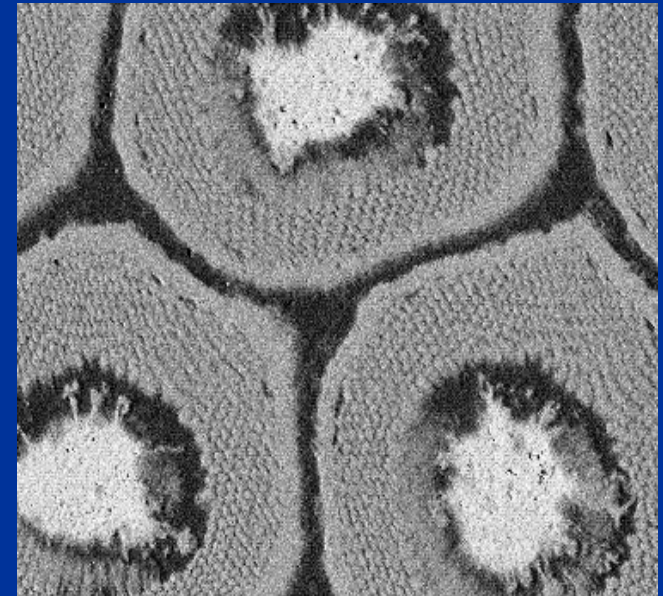
Using HD1 as an example physically $\sim 70 \mu\text{m}$
for the sub-element at 12T

$$B_o \sim 0.08\text{T}$$

The Flux Jump Field B_{FJ}

$$B_{\text{FJ}} = (2\mu_o C_v J_c / (-dJ_c/dt))^{1/2}$$

$$B_{\text{FJ}} \sim 0.16\text{T}$$





Windings, Cables, Strands, and Sub-Elements

Sub-Element Stability Estimate Calculations

> Surface Shell (Nb₃Sn)

$$- h = K/w = 5 \times 10^{-2} \text{ W/mK} / 16 \mu\text{m}$$

$$\sim 3.1 \times 10^3 \text{ W/m}^2\text{K}$$

$$\tau_0 = C_v a / h = 206 \text{ s}$$

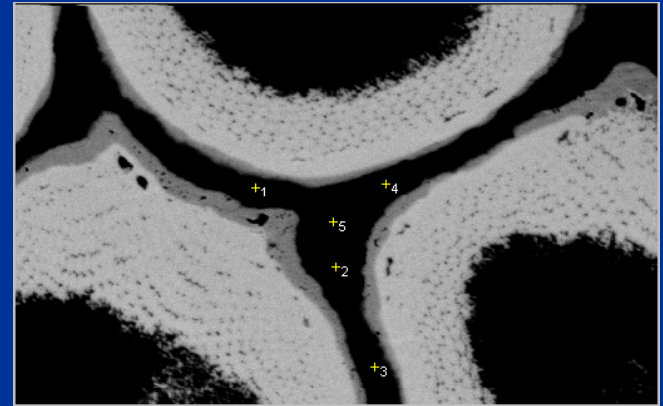
> If 10% of sub-element shell were bronze fins:

- “ τ_0 ” would decrease $\sim 10^3$

- aids de-coupling magnetically as well

$$D_\theta(\text{Cu}7.5\text{w/oSn}) = 7 \times 10^{-2} \text{ m}^2/\text{s}$$

$$D_m = 8 \times 10^{-2} \text{ m}^2/\text{s}$$



Position 1

Elmt	Spect.	Element	Atomic
Type	%	%	
Cu K	ED	270.19	97.94
Nb L	ED	5.79	1.44
Sn L	ED	3.21	0.62
Total		279.19	100.00

Position 2

Elmt	Spect.	Element	Atomic
Type	%	%	
Cu K	ED	277.41	99.45
Nb L	ED	0.49*	0.12*
Sn L	ED	2.25	0.43
Total		280.15	100.00

* = <2 Sigma

Position 3

Elmt	Spect.	Element	Atomic
Type	%	%	
Cu K	ED	264.84	96.64
Nb L	ED	11.82	2.95
Sn L	ED	2.09	0.41
Total		278.75	100.00



Windings, Cables, Strands, and Sub-Elements

> If the FJ reduces the composites effective “ ρ ”

D_m would be smaller by 10 (Yasukochi ‘81)

> Another more conservative approach would

suggest: if “ B_p ” were 0.16T then

- $\mu_o J_c a_{eff} = 0.16T$ or $a_{eff} = 16\mu m$

- $\sim 32\mu m$ diameter filaments

> This appears to be possible in the near future!

> However present operations appear to have

• Exceeded % short sample predicted by

• Stability parameter “ β_t ”

$$\beta_t = \mu_o \lambda^2 J_c^2 a^2 / C_v (\theta_c - \theta_o)$$

Manufacturers More J_c Please!

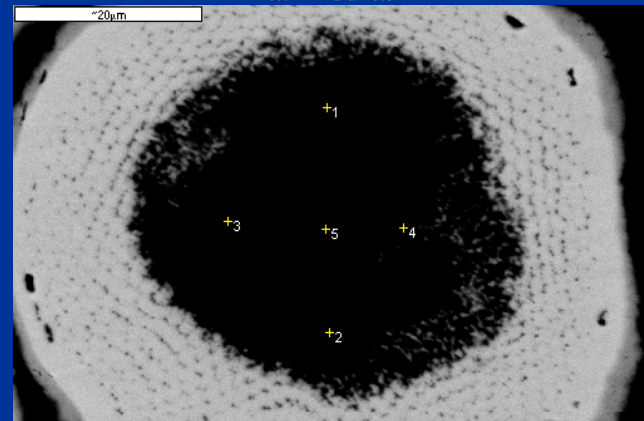
6555 Cu-Sn Compositional Analysis

100 hours at 210 °C

48 hours at 340 °C

100 hours at 650 °C

0.7 mm diameter



Position 1

Elmt	Spect.	Element	Atomic
Type	%	%	
Cu K	ED	256.37	95.59
Nb L	ED	0.45*	0.11*
Sn L	ED	21.54	4.30
Total		278.36	100.00

* = <2 Sigma

Position 2

Elmt	Spect.	Element	Atomic
Type	%	%	
Cu K	ED	251.66	95.06
Nb L	ED	2.23	0.58
Sn L	ED	21.60	4.37
Total		275.49	100.00

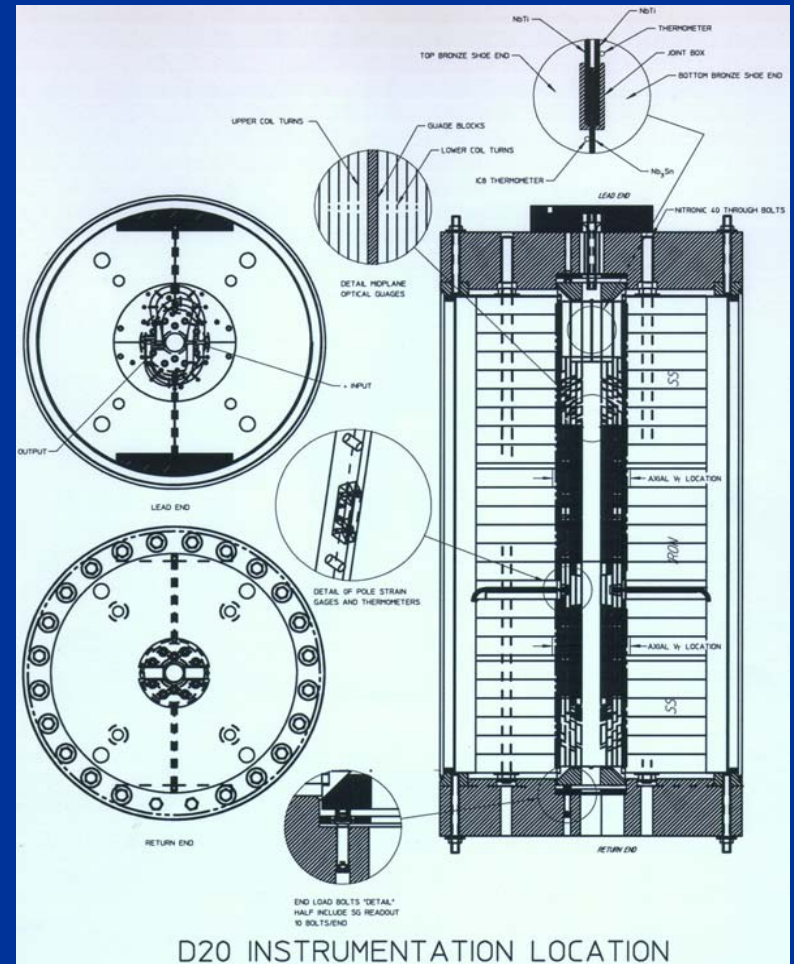
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Training Cos Θ coil - D20

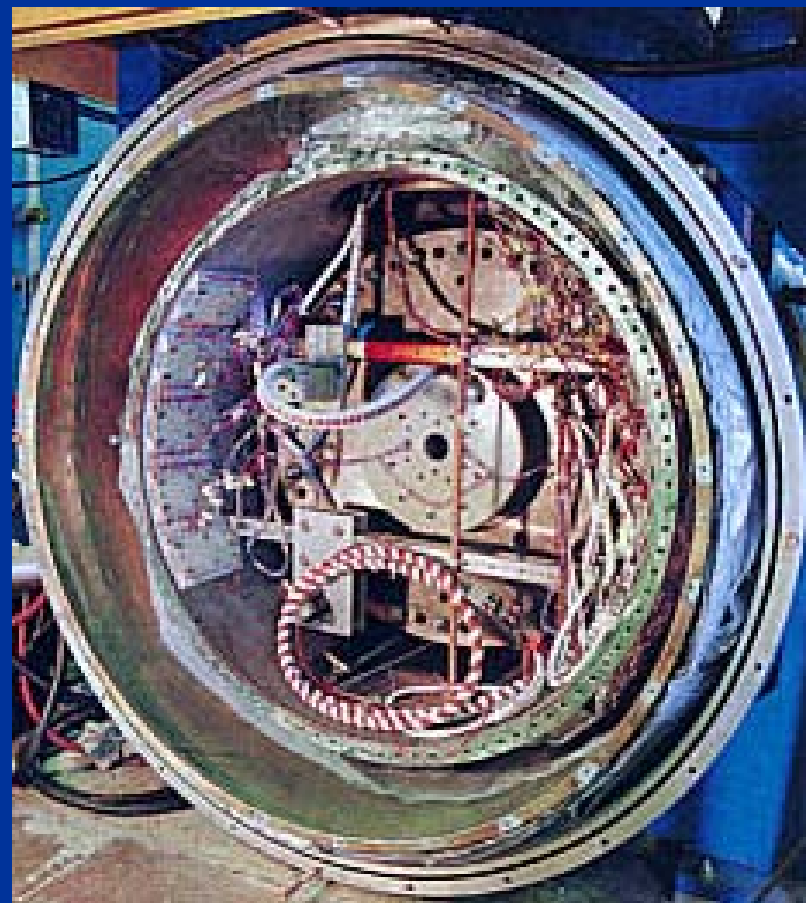
- $J_{\text{non cu}}(12\text{T}, 4.2\text{K}) \sim 735\text{A/mm}^2$
- Preload < Lorentz load
~100MPa vrs 140MPa cal. Lorentz
- Pole/1st turn Separation
>pole turns account for 42% of quenches and 23 of 1st 25
- Soft Support for a bottom outer coil lead which is the source of 33% quenches





Training Cos Θ coil - D20

- Protection Heaters adequate
peak quench spot temperature
<235K
- Windings very Rugged >100
quenches driven and natural no
apparent problems
- Low End Loads less than 5%
of calculated load measured at end
- Record Dipole Fields 12.8T
, 4.2K and 13.5T , 1.9K

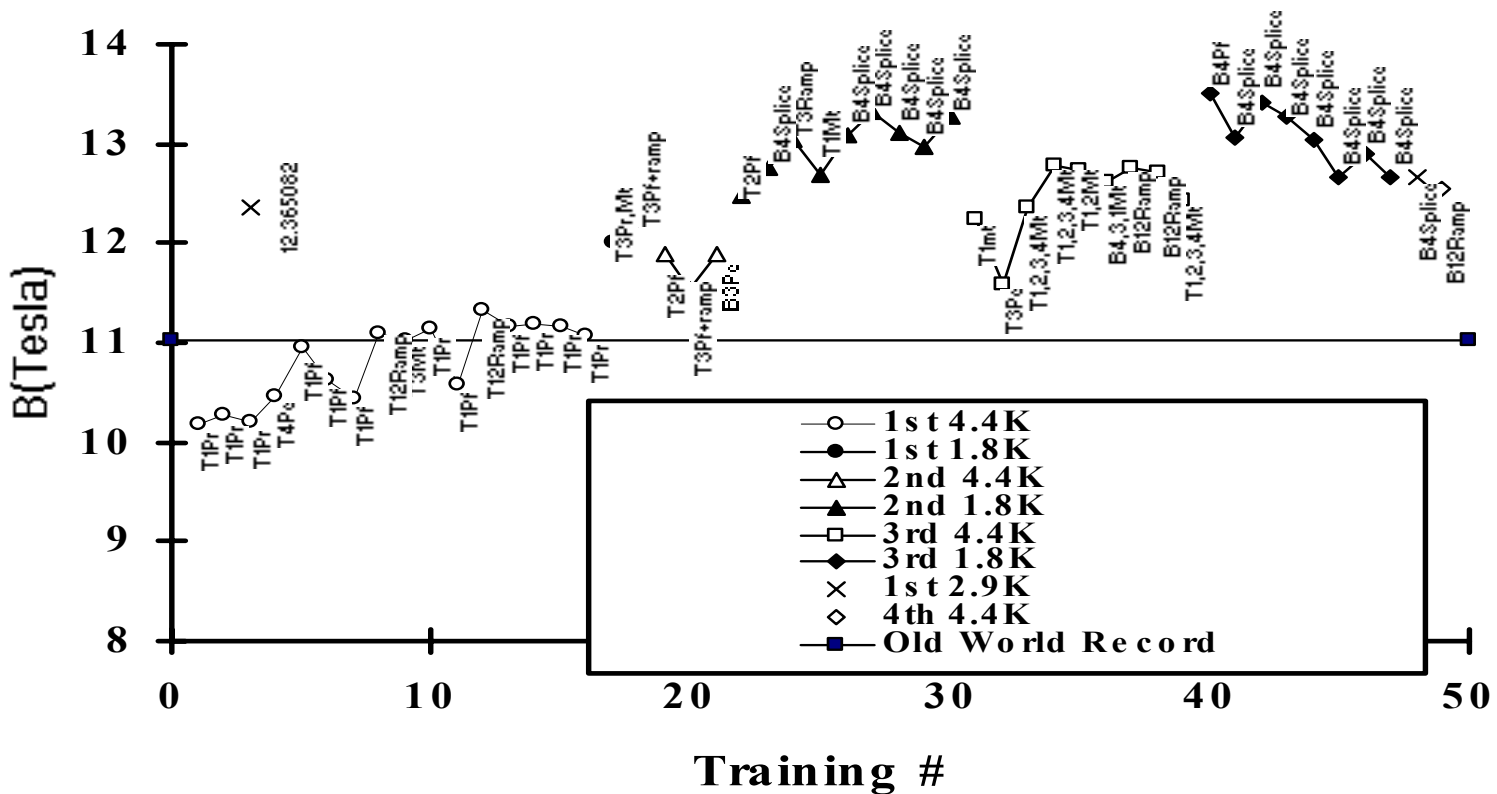


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Training Cos Θ coil - D20

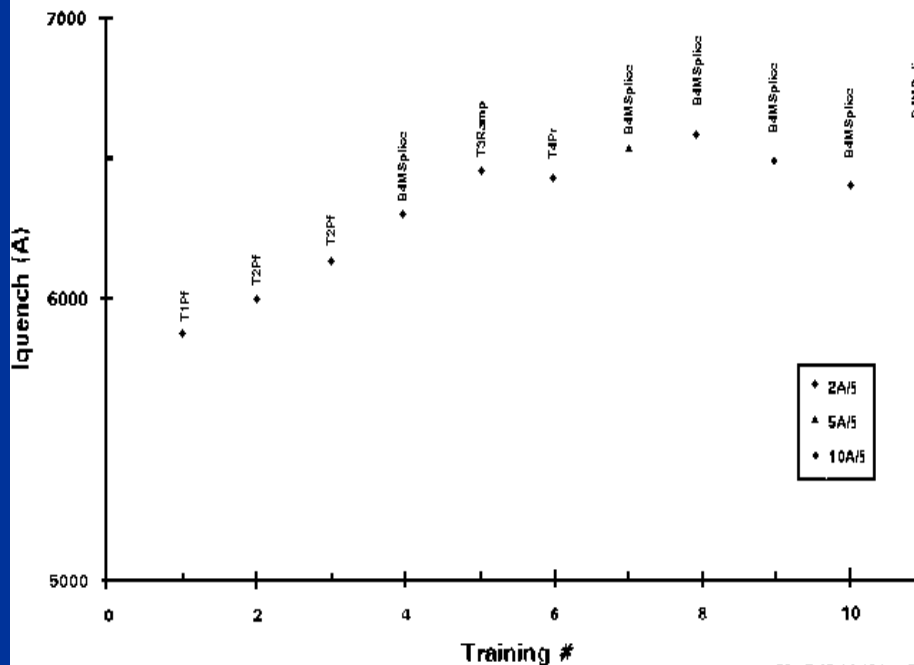
D20: Training History





Training Cos Θ coil - D20

D20:"1.8K" Training History



Super Fluid Quenches

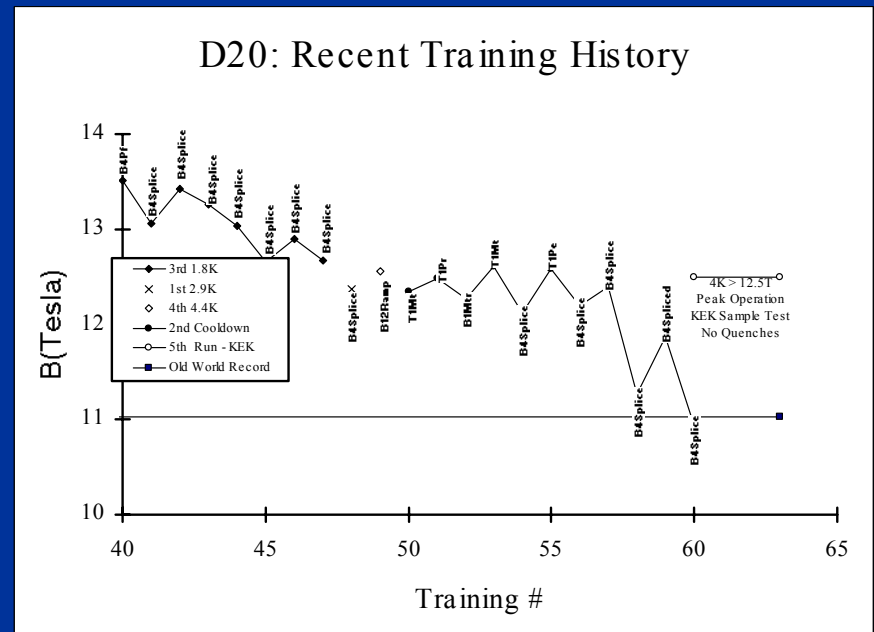
- Training still at Super Fluid peak field 13.5T vrs ~13.8T SS
- S.F.T. shortened the 4K training , but did not eliminate it
- Problem with the outer coil lead stability first appears at super fluid temperatures!



Training Cos Θ coil - D20

- After fourth cool down, the magnet ran reliably at 12.5T (12.8T measured short sample)
- The coil had a 20w margin at 12.5T 4.5K
- **Summary:** There were two clear problems:
 - Bonding to post &/or low pre-load
 - Excess soft insulation leading to conductor motion
- These account for 75% of the 60 training Quenches

Apparently Stable!

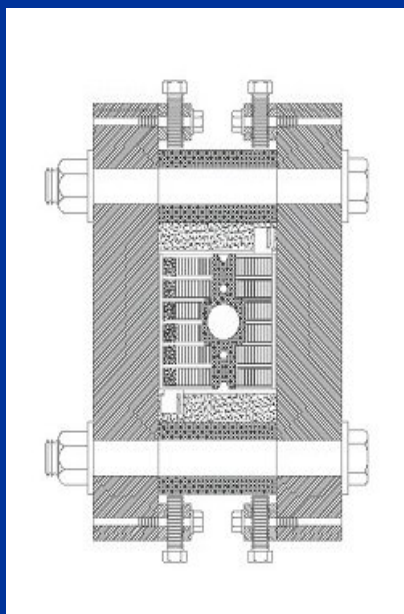




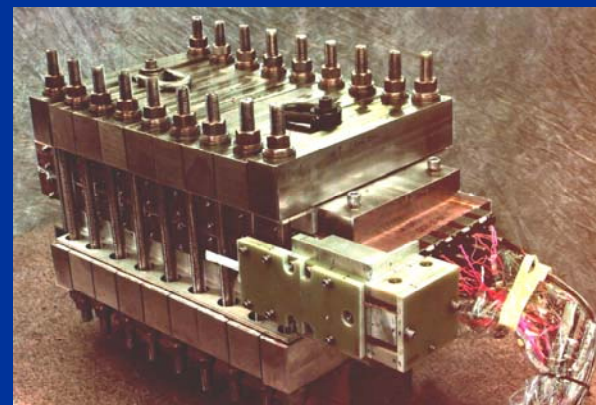
Training Common Coil - RD2-01

- First Av. “J” Common Coil
 - > Pre-loads varied over large range
 - > Peak Field ~6T
 - > Loads varied over many configurations
- * No Training Observed!

Magnet configuration	Load at 300K	300K	4K	4K
	Horizontal	Vertical	Horizontal	Vertical
RD-2-01	30 MPa	30 MPa	50 MPa	30 MPa
RD-2-02	6 MPa	6 MPa	50 MPa	30 MPa
RD-2-03	6 MPa	6 MPa	21 MPa	12 MPa



RD2- Series Assembly

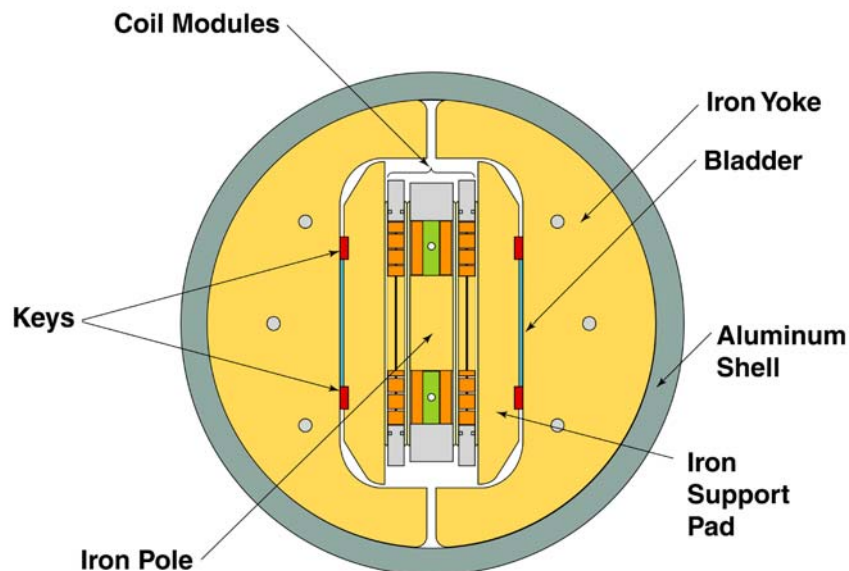
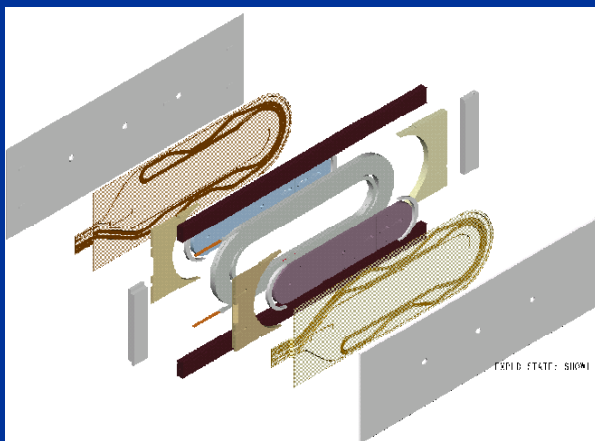




Training Common Coil RD-3

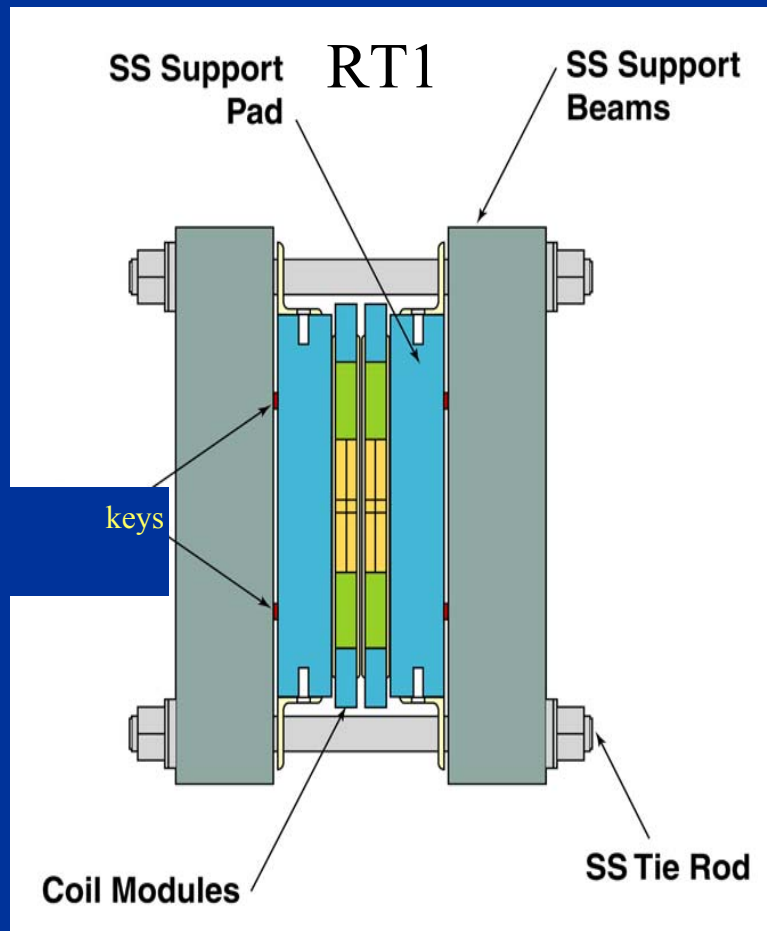
14 Tesla Common Coil Design

- Main coil spacing 25 mm
- Quench field at 4.2 K 14.4 T
- Quench Current 10.8 kA
- Number of layers/mod. 2
- Coil modules 3
- Straight section length 500 mm



Training Common Coil RT1

- Outer Module's Configuration



Coil Module Loading and cycling



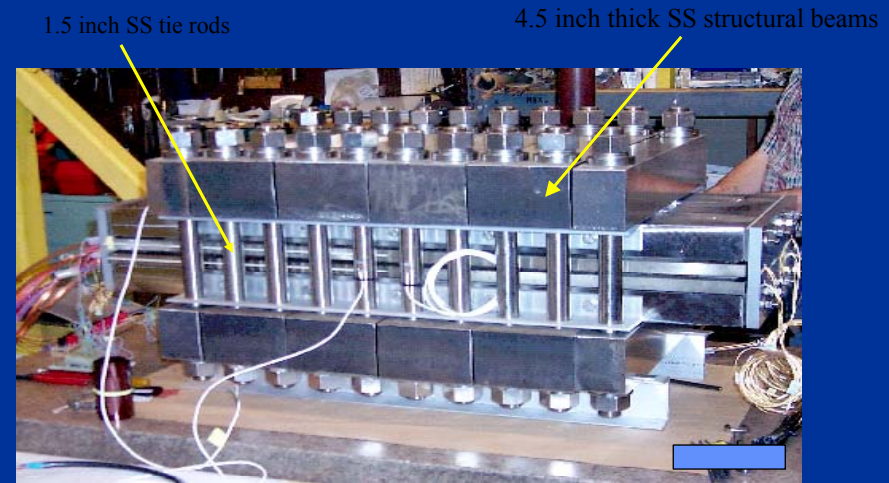
- > Modules preloaded repeatedly
- > Weld shrinkage increased load



Training Common Coil RT1

- RD3 Module Pretesting alias RT1
- High Fields (12T) no gap between
- Large Forces between Modules
~6.9 MN or 775 tons
- Large Module separation ~1.8mm
- 3 Training Quenches 96%,
93%, and 98% of short sample

RT1 preloaded in Support





Training Common Coil RD-3

Features

- Large Force 3×10^6 lbs horizontal
- Conductor Stress > 100 MPa

Performance

- Previously quenched & virgin outer modules displayed similar behavior
- Both outer modules began quenching at a lower Lorentz load than the trained one before (> 13.7 T)
- First time the inner surface of the outer modules were loaded!
- The inner and 2 outer modules had nearly identical short sample limits.

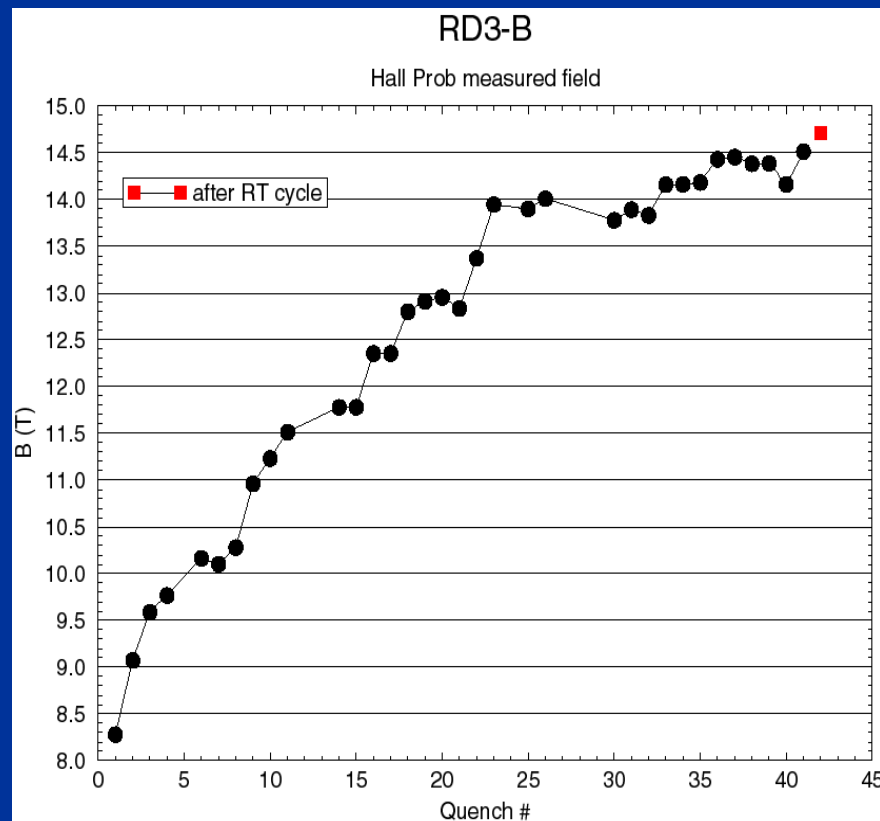
RD3b awaits Test





Training Common Coil RD-3

- Quench history slope changes when the quench origin switched from inside to outside.
- Moderate improvement of “ I_q ” after a full thermal cycle (a.k.a. D20).
- RD3c (different middle module with larger aperture) had all but 2 quenches in the already tested outer modules.
- RT1 was the only configuration of this series that had a great training history

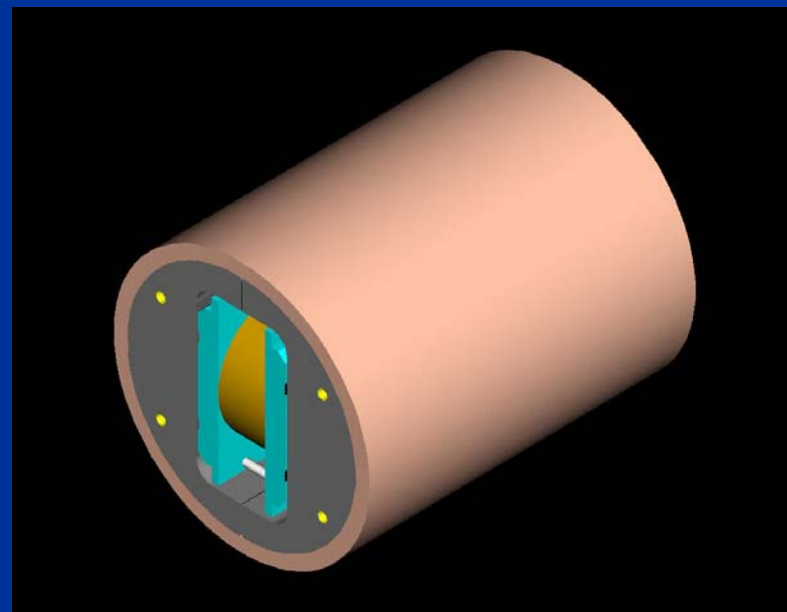




Training Sub-scale Model Program

Technology development and increased productivity
with a parallel test program

- Scaled version of full-size magnet
 - Approx. 1/3 scale
- Field range of 9 – 12 Tesla
- Simple two-layer racetrack coils
 - 5 kg of material per coil
- Streamlined test facility
 - Small dewar (no refrigerator)





Training Sub-Scale Model Series

Sub-Scale Model Magnet Series

- First sub-scale magnet (SM01a) was to have the equivalent geometry as RT1
- First version “SM01a” had a nominal load of 13,000 psi
- Second version “SM01b” had a minimum load of 1,500 psi
- The second coil module “SC02” ‘s skins were not welded although pre-stressing cycles were done

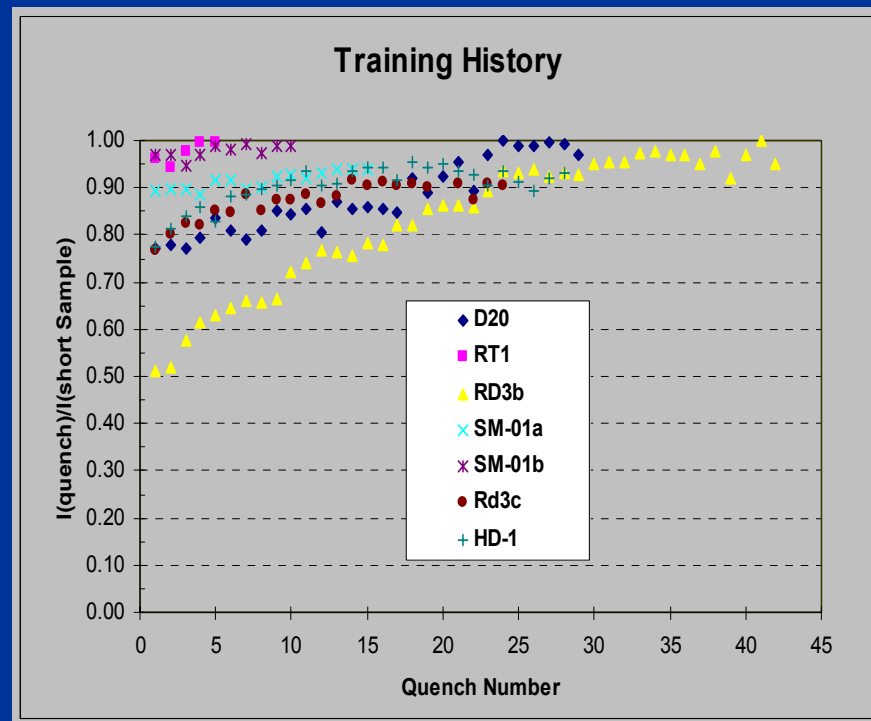




Training -Normalized Quench History

Summation of all coil's
Performance Normalized

- Poorest Peak Performance RD3c & SM01a (both candidates for S.F. training)
- RD3b displayed the poorest training history
- Best Performance was RT1 & SM01b
 - Both had <50% Lorentz load
 - Both had one face loaded the other face not
 - Both had experienced large deflections under field



Note for clarity RD-2-01, RD-2-02, and RD-203 are not plotted they would be at 1.0 for the 1st quenches.



Training

MAGNET	D20	RT1	RD3b	RD3c	SM01	HD1
Jc (A/mm²)						
(12T, 4.2K)	960, 1600	-	2043	2014	-	-
	1627	2143	2143, 1754	2143, 1754	2260	3000
Jcu (A/mm²)						
(12T, 4.2K)	2240, 1481	-	2270	2319	-	-
	1535	1367	1367, 1329	1367, 1329	2774	1400
No. strands	37	-	40	31	-	-
	47	26	26	26	20	36
No. turns	16+26	-	50	16	-	35
	40+56	49	49	49	20	35
Cu/SC	0.43, 1.08	-	0.90	0.90	-	0.72
	1.06	1.64	1.64, 1.35	1.64, 1.35	0.81	0.96
Strand diam. (mm)		0.753	-	0.800	0.800	-
	0.482	0.800	0.800	0.800	0.710	0.8
Thickness (mm)		1.356	-	1.386	1.396	-
	0.873	1.408	1.408	1.408	1.270	1.546
Width (mm)	14.45	-	17.20	13.32	-	-
	11.63	11.34	11.34	11.34	7.80	16.01
Pitch length (mm)		93.50	-	119.80	93.40	-
	81.28	81.28	81.28	81.28	54.88	81.28

* Cable values are an average of the known strand values.

** When two rows exist, the upper row is associated with the inner module.
(if it existed) Lower row outer module

*** The second of two values separated by comma refers to an identical coil
with a different conductor

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Training What have we learned?

Standard Age olde Wisdom

- Hold Winding package under compression in all dimensions that is greater than the Lorentz Load plus a safety factor. I.e. do not leave any place for the winding to go.
 - Problem This may be very difficult to obtain in multipole magnets
 - and/or
 - Alternate Strategy and/or Scheme
- Remove the bond between the windings and support surfaces that are not supporting the Lorentz Load (particularly separating ones)
- Moderately load the winding enough to remove the fluff. I.e. $< \text{MPa}$ and that the windings are in contact with the Lorentz force bearing surface
- Allow the coil to move as much as the desired field quality will permit and it is in contact with the supporting surface from the start of energizing.
- Low RRR is not a problem if fairly uniform and ≥ 10 . I.e. both stability and protection are aided by the bronze's presence.
- Filament sizes in excess of a $100 \mu\text{m}$ for “MJR” or “RRP” process are on the edge of stability and therefore caution is in order

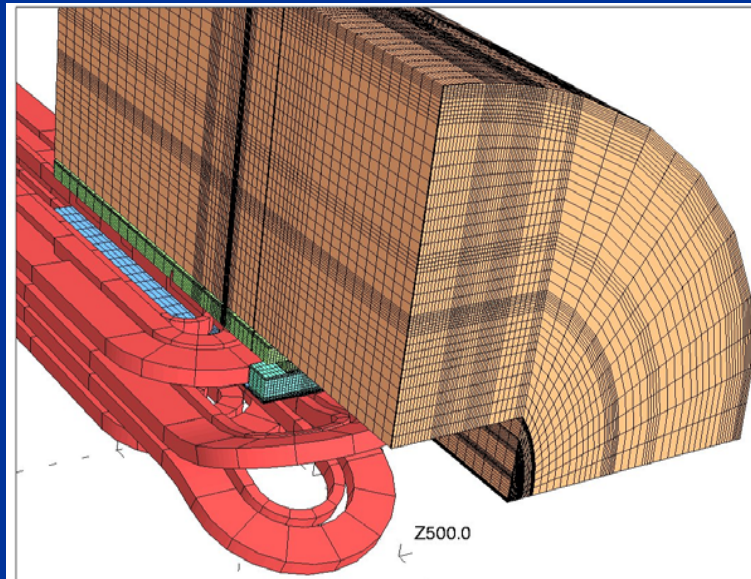


Training Block coil - TAMU-4

"Stress managed"

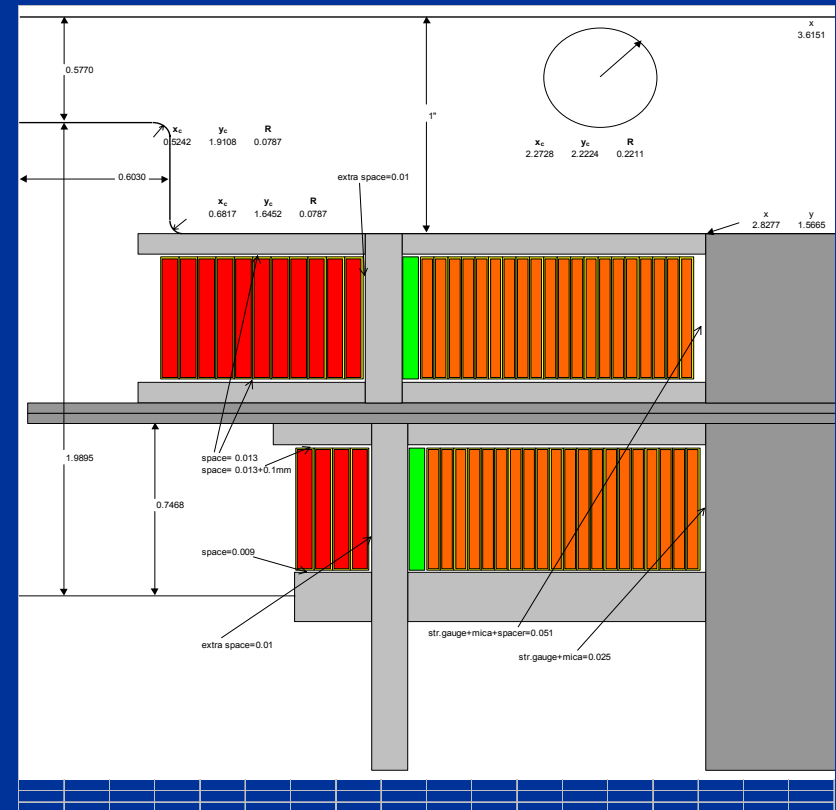
Training Improvements Attempted

- Two Surfaces not bonded & possibly a third
- Moderate loads on winding (spring only) During heat treatment and before powering



Cross Section of a coil quadrant

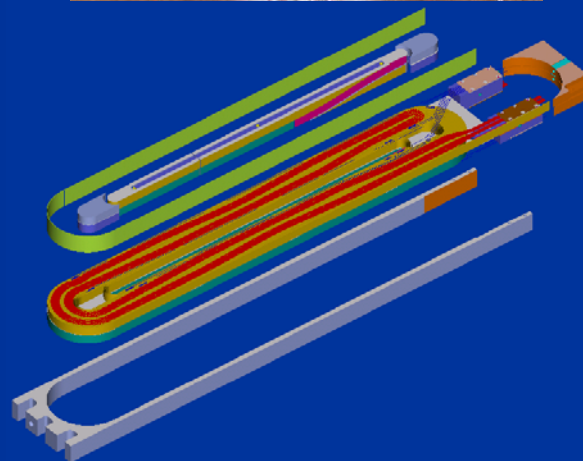
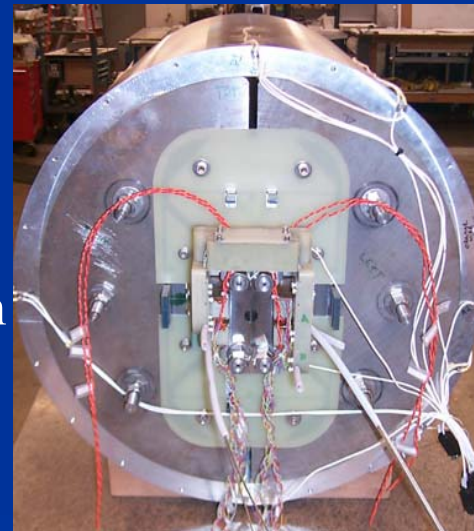
Green bars in front of turns are springs





Training Block Coil - HD-1

HD1 is the present generation LBNL high field dipole magnet winding being investigated for its potential. HD1's main objective is field not training performance, but it certainly has been recorded. To date the magnet has achieved a maximum bore field of $15.97 \pm 0.049\text{T}$ at 4.4K

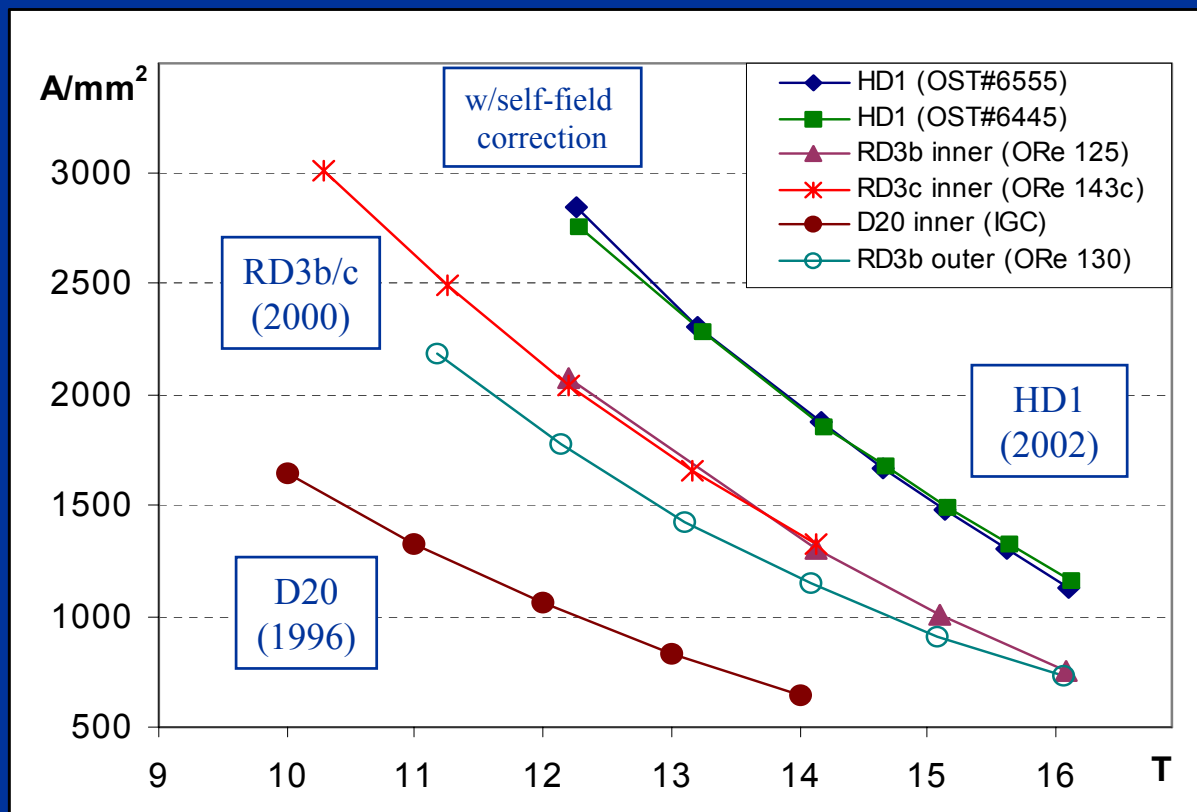


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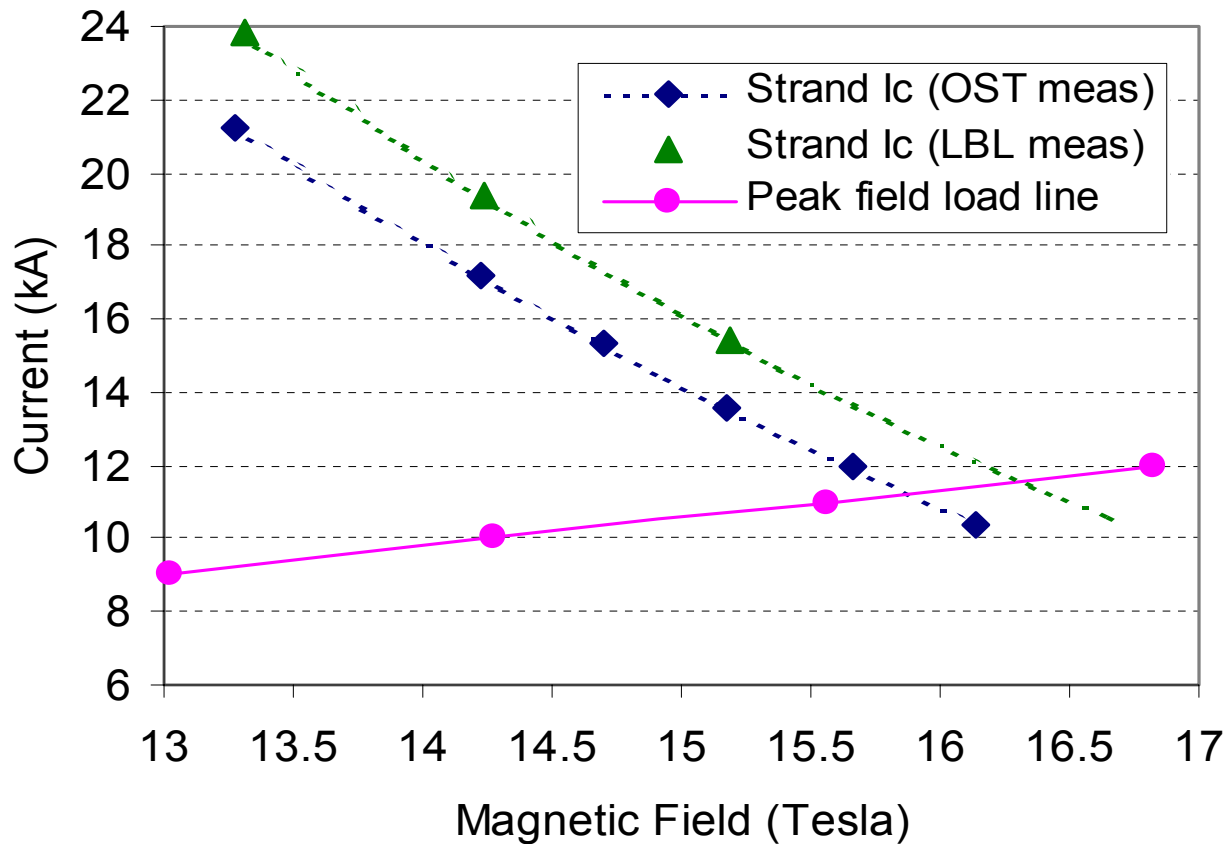


HD1 Conductor





HD1 Conductor





Conditions Assumed in Talk

- Protection to be accomplished by a close proximity heater
- Highly efficient coil winding package $J_{\text{eff}} > 1000 \text{ A/mm}^2$
currently: $J_{\text{eff}} \sim 1500 - 2000 \text{ A/mm}^2$
- Examples given will be limited to Nb_3Sn coils. “Should be applicable to other A-15’s”
- Heater constructed composites of Kapton/SS(cu)/ Kapton plus glue



Definitions

Conductor MIIT's	≡	$10^6 \text{ Amp}^2 \text{-sec}$ to reach 450K a) measured b) adiabatic calculation
Critical ramp rate	≡	Rate of current change at which the conductor's temperature rise exceeds it's critical temperature at $\sim 0.9 I_c$
Minimum Protection Winding volume(conductor length) transitioning	≡	That length of conductor which will result in a L/R time constant period that will stay within the conductor MIIT's budget
RRR	≡	Resistance Ratio of the conductor between room temperature & T_{c2}^+



Typical Design of a Heater for a Nb_3Sn Race Track Coil

For example HD-1

Conductor Parameters:

36 strand cable

0.8 mm strand diameter

$J_c(\text{non-cu}, 12\text{T}, 4.3\text{K}) = 3000 \text{ amps/mm}^2$

Typical design input:

Quench output page

Typical MIITs Curve:(RD-3 shown)

Quench's MIIT's Curve for HD-1 is 19 Miits instead of 12.4

First order heater considerations HD-1:

Inductance = 7mh

$L/R = ?$ at 11.2kA/turn yields 125 MIIT's/second

MIIT's limit "Quench" = 19.2 - Room Temperature

$\Rightarrow 157 \text{ milliseconds}$

$-\frac{40}{117}$ " detection & diffusion

$\Rightarrow 0.235 \text{ seconds} = t(\text{effective})$

$R = 0.007/0.235 \sim 0.034 \text{ ohms}$

HD-1 coil's room temperature resistance = 0.460 ohms

20K R(expected) = 0.02 ohms

20K R(measured)= 0.031 " note the dramatic "RRR" effect

$\Rightarrow 1/4$ of the coil driven normal will work

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Typical Design of a Heater for a Nb_3Sn Race Track Coil(continued)

$\Rightarrow 0.235 \text{ seconds} = t(\text{effective})$

$R = 0.007/0.235 \sim 0.031 \text{ ohms}$

For example HD-1 continued

HD-1 coil's room temperature resistance = 0.460 ohms

20K $R(\text{measured}) = 0.0321 \text{ ohms}$

Now a look at the possibility of a quench back!

Assume 1/2 of the magnet is driven normal at ~ 40 milliseconds

Then $L/R = 0.007/0.016 \sim 0.11 \text{ sec}$

or $dI/dt = -25,600 \text{ amperes/sec.} \rightarrow 96,000 \text{ amperes/sec.}$

The slowest rate is 100 greater than that required to quench HD-1 at 25% of it's plateau current!

\equiv **Quench Back** will occur < 30 milliseconds



Protection of D20

A very conservative approach was taken:

70% of the magnet volume was under heaters

The power level was set for Super Fluid operation

Layer 1 = 53 watts/cm²

Layer 2 = 23 “

Layer 3 = 29 “

Layer 4 = 27 “

The highest average temperature Quench was: outer turn = 165K - 185K

inner turn = 80K - 120K

The MIIT's curve predicted: outer turn = 234K ; inner turn = 152K



“Quench” Code Input/Output for MIITs

COMPONENT PROPERTIES

FRAC	THETA	A	AEX	B	BEX	C	CEX	D	DEX	RMAG
.4090	.00	.4250E-07	.0000	.1670E-11	2.6900	.8000E-05	3.0000	.0000E+00	.0000	1.0000
.4090	40.00	.4250E-07	.0000	.1670E-11	2.6900	.2300E-02	1.5000	.0000E+00	.0000	1.0000
.4090	100.00	.1380E-08	1.2300	.0000E+00	.0000	.3000E+01	.0000	.1200E-02	1.0000	1.0000
.0710	.00	.1700E-05	.1200	.1670E-11	2.6900	.8000E-05	3.0000	.0000E+00	.0000	1.0000
.0710	40.00	.1700E-05	.1200	.1670E-11	2.6900	.2300E-02	1.5000	.0000E+00	.0000	1.0000
.0710	100.00	.1700E-05	.1200	.0000E+00	.0000	.3000E+01	.0000	.1200E-02	1.0000	1.0000
.2120	.00	.1000E+11	.0000	.0000E+00	.0000	.1000E-03	2.4000	.0000E+00	.0000	.0000
.2120	15.00	.1000E+11	.0000	.0000E+00	.0000	.4400E-02	1.0300	.0000E+00	.0000	.0000
.3080	.00	.6100E-04	.0000	.0000E+00	.0000	.7400E-04	2.2700	.0000E+00	.0000	.0000
.3080	80.00	.6100E-04	.0000	.0000E+00	.0000	.5400E+00	.2400	.0000E+00	.0000	.0000

1

INITIAL CURRENT= 14000.00 INIT. PROT. R.= .0550 GAMMA .00 R. SWITCH=3000000.00 COIL IND. .0180

INIT. VELOCITY= 7294.46 UNIT CELL AREA = .188900 INITIAL TEMPERATURE = 4.5000

ALPHA = .00500 INIT. X VELOCITY= 515.7963 EPSILON= .78000 INIT. Y VELOCITY= 6442.2940

X COIL DIMENSION= 8.00 Y COIL DIMENSION= 1.16 Z COIL DIMENSION= 172.30

COORDINATES OF SOURCE X= 1.00 Y= .00 Z = 86.20

BREAKER DELAY TIME = .40 INITIAL MAGNETIC FIELD= 117.600KG

time	current	coil resistance	delta volume	ext. voltage	int. energy	int. voltage	theta	isqdt
0.001	13999.89	1.43E-04	2.54E+01	0	27.95	2	7.19	0.2
0.002	13999.69	2.59E-04	2.05E+01	0	50.71	3.62	10.47	0.4
0.003	13999.33	4.54E-04	3.42E+01	0	88.9	6.35	14.76	0.6
0.004	13998.76	7.34E-04	4.79E+01	0	143.91	10.28	23.82	0.8
0.005	13997.9	1.11E-03	6.15E+01	0	216.69	15.48	31.62	1
0.006	13996.68	1.57E-03	7.52E+01	0	307.79	21.99	36.79	1.2
0.007	13995.05	2.10E-03	8.19E+01	0	410.86	29.35	40.7	1.4
0.008	13992.99	2.66E-03	8.22E+01	0	520.18	37.17	44.04	1.6
0.009	13990.44	3.28E-03	8.71E+01	0	642.03	45.88	47.19	1.8

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Design Input necessary for Protection Stainless Steel Heater Analysis

Table

Integrated Stainless Steel Specific Heat Versus Peak Temperature

Temperature Adiabatic(K)	Energy/unit volume joules/cubic centimeter
100	80
200	316
300	642
400	1034
500	1494
Kapton Failure 770K	2700
Typical Resistivity (Stainless Steel) RRR	50 micro-ohm-cm 1.5
Typical Time constants (1/e) Heater pulse	30 – 100 milliseconds
Typical detection plus thermal Diffusion time at 70% short Sample (typically the peak MIIT's value)	~40 milliseconds
Typical Heater Power supply Parameters (x2 if stacked)	450v 2 to 20 millifarad

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Summary of Typical Process Protection Heater Design

Obtain MITs curve for magnet	Calculate from “Quench” code or Measure
Calculate minimum coil volume(conductor length) I (operate), L (millihenries)	
Design heater area greater than necessary Heater area calculated to switch minimum coil volume(conductor length)	
Residual Resistance Ratio (conductor)	Most effective 10 - 20*
Heater design resistances calculated	ohms to few 10's of ohms
Temperature (heater) targets	150K to 200K
Wattage (heater) at the surface	$\geq 20\text{w/cm}^2$ for LHe & $\geq 40\text{w/cm}^2$ for Super-fluid He
Time (heater) constants	30 millisec. to ≤ 100 millisec.
*New Knob discovered by serendipity	
An efficient heater should:	especially pertinent to longer magnets
Include an active length (non-cu plated) ≥ 1 cable transposition length	
Minimum heater thickness (ss)	13 micron preferred, but 25 micron is normal
Min. thickness Kapton under layer and/or 25 microns (≥ 3 kV checked)	
Alumina filled Kapton (x2 thermal conduct.)	25 “ “ thermal diffusion time $\sim 20\text{-}25\text{ms}$



Training Summary

Olde Method

---Works---

- > Provided Structure is able to preload the windings in all directions, such that the coil can not move under any Lorentz load permutation.

Newer Strategy

--Works under careful control--

- > Do not bond winding to any surface that is possible to be in shear or non contact with I.e. not surfaces that become unloaded like $\cos\theta$ winding poles, solenoid spool
- > Control integration of the Lorentz forces to limit winding deflections (a field quality issue) I.e. load enough to remove fluff and insure support contact (springs?)
- > Higher the metal packing fraction the lower the deflection per given load. (higher ampere-turn) This results in a higher modulus and lower voltages
- > Avoid magnet designs with parallel surfaces under load in contact with winding



State of Present High Field Magnet Coil's Protection

Protection Heater Mode

- The Heater design is per unit length
provided the heater is segmented properly
- Therefore heaters can be effective on “Long or Short” magnets
- The length limit using this protection mode is thermal mechanical
limited by stresses caused by differences in coil's temperature and the support structure
Later designs attempted <100K
- Overall “J's” in the range of 2000 amperes/mm² appear possible at this time
although results for windings in the 1000 amperes/mm² range are available.